Pseudospheres from singularity theory view point with a classification of 2-soliton surfaces (j/w with Yutaro Kabata) <u>Toshi Fu</u>kui (Saitama University) 16:45-17:15,26 September,2023 Workshop for Mathmatics for Industry 25-29 September, 2023

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Surfaces in
$$\mathbb{R}^{3}$$

 $\varphi : \mathbb{R}^{2} \longrightarrow M = \varphi(\mathbb{R}^{2}) \subset \mathbb{R}^{3}, C^{\infty}$
 $E = \langle \varphi_{u}, \varphi_{u} \rangle, F = \langle \varphi_{u}, \varphi_{v} \rangle, G = \langle \varphi_{v}, \varphi_{u} \rangle$
 $L = \langle \varphi_{uu}, \nu \rangle, M = \langle \varphi_{uv}, \nu \rangle, N = \langle \varphi_{vv}, \nu \rangle$
where ν is a unit normal.
The first fundamental form
 $I = E du^{2} + 2F du dv + G dv^{2}$

uu

The second fundamental form

/ =

 $II = L du^2 + 2M du dv + N dv^2$

Chebyshev' net

A pseudosphere is a surface with constant negative Gauss curvatures. We can assume that they have Gauss curvature -1 up to similarity transformations. For a surface with K = -1, we can take the asymptotic coordinate (u, v) with the following fundamental forms:

 $I = du^{2} + 2\cos\phi \, du \, dv + dv^{2}$ $II = 2\sin\phi \, du \, dv$

where ϕ is the asymptotic angle. Gauss-Coddazi equation becomes sine-Gordon equation:

 $\phi_{uv} = \sin \phi$

Curvature coordinate is given by

$$x=\frac{u+v}{2}, \quad y=\frac{u-v}{2},$$

The fundamental forms are

$$I = \cos^2 \frac{\phi}{2} dx^2 + \sin^2 \frac{\phi}{2} dy^2$$
$$II = \frac{1}{2} \sin \phi (dx^2 - dy^2)$$

The principal curvatures are

$$an rac{\phi}{2}, ext{ and } -\cot rac{\phi}{2}$$

Ridge and flechodal

Let v_i denote a principal vector of a surface and let κ_i denote the corresponding principal curvature of a surface.

A point P on a surface is v_i -ridge if $v_i \kappa_i(P) = 0$.

A point P on a surface is fleenodal if there is a line with at least 4 point contact with the surface at P.

- 1. The level sets of ϕ , κ_1 and κ_2 containing P are equal.
- 2. The differentials of the principal curvatures are given as follows:

$$\partial_{x}\kappa_{1} = \frac{\phi_{x}}{1 + \cos\phi}, \qquad \partial_{y}\kappa_{1} = \frac{\phi_{y}}{1 + \cos\phi}, \\ \partial_{x}\kappa_{2} = \frac{\phi_{x}}{-1 + \cos\phi}, \qquad \partial_{y}\kappa_{2} = \frac{\phi_{y}}{-1 + \cos\phi}$$

So ∂_x -ridge (resp. ∂_y -ridge) is given by $\phi_x = 0$ (resp. $\phi_y = 0$). (A level of ϕ has a horizontal (or vertical) tangent.) Flecnodal point on pseudosphere is given by $\phi_u \phi_v = 0$. (i.e., A level of ϕ has a diagonal (or anti-diagonal) tangent.)

Backlünd transformation

We say $ilde{\phi}$ is Backlünd transformation of ϕ if

$$\left(\frac{\tilde{\phi}+\phi}{2}\right)_{u} = \lambda \sin \frac{\tilde{\phi}-\phi}{2}, \quad \left(\frac{\tilde{\phi}-\phi}{2}\right)_{v} = \lambda^{-1} \sin \frac{\tilde{\phi}+\phi}{2}. \quad (1)$$

where $\lambda = \tan \theta / 2$. θ is in the next sheet. If ϕ is a solution of sine-Gordon equation, so is $\tilde{\phi}$.

 $\{\text{sol. of sine-Gordon}\} \xrightarrow{BT} \{\text{sol. of sine-Gordon}\}$

Geometric BT

We say

$$M\longrightarrow \widetilde{M}, \quad p\longmapsto \widetilde{
ho},$$

is gemetric BT, if

- The line $\overline{p\tilde{p}}$ is in T_pM and also in $T_{\tilde{p}}M$.
- $d(p, \tilde{p})$ is constant (= r).
- the unit normals ν_p and $\tilde{\nu}_{\tilde{p}}$ has a constant angle θ , that is $\langle \nu_p, \tilde{\nu}_{\tilde{p}} \rangle = \cos \theta$.

Geometric BT between K = -1 surfaces is given by

 $\tilde{\varphi} = \varphi + r \Big(\frac{\cos \tilde{\phi}/2}{\cos \phi/2} \varphi_x + \frac{\sin \tilde{\phi}/2}{\sin \phi/2} \varphi_y \Big), \ r = \sin \theta$

and it preserves Chebyshev's nets.

Bianchi's permutability If ϕ_i (i = 1, 2) satisfies $\left(\frac{\phi_i + \phi}{2}\right)_u = \lambda_i \sin \frac{\phi_i - \phi}{2}, \quad \left(\frac{\phi_i - \phi}{2}\right)_v = \lambda_i^{-1} \sin \frac{\phi_i + \phi}{2},$ and $\tilde{\phi}$ satisfies

 $(\lambda_2 - \lambda_1) an rac{\overline{\phi} - \phi}{4} = (\lambda_2 + \lambda_1) an rac{\phi_2 - \phi_1}{4},$

then

$$\begin{pmatrix} \frac{\tilde{\phi} + \phi_1}{2} \end{pmatrix}_u = \lambda_2 \sin \frac{\tilde{\phi} - \phi_1}{2}, \quad \left(\frac{\tilde{\phi} - \phi_1}{2} \right)_v = \lambda_2^{-1} \sin \frac{\tilde{\phi} + \phi_1}{2}.$$
$$\begin{pmatrix} \frac{\tilde{\phi} + \phi_2}{2} \end{pmatrix}_u = \lambda_1 \sin \frac{\tilde{\phi} - \phi_2}{2}, \quad \left(\frac{\tilde{\phi} - \phi_2}{2} \right)_v = \lambda_1^{-1} \sin \frac{\tilde{\phi} + \phi_2}{2}.$$

Soliton 0-soliton \xrightarrow{BT} 1-soliton \xrightarrow{BT} 2-soliton $\phi = 0$ $\phi_{\lambda} = 4 \tan^{-1}(\lambda u + \lambda^{-1}v)$ $\phi_{\lambda_{1},\lambda_{2}} = 4 \tan^{-1}\left(\frac{\lambda_{1} + \lambda_{2}}{\lambda_{2} - \lambda_{1}} \cdot \frac{\sinh \frac{\xi_{1} - \xi_{2}}{\cosh \frac{\xi_{1} - \xi_{2}}{2}}\right)$ line

Beltrami's pseudosphere Dini's pseudosphere

2-soliton surfaces

Singular locus of φ

Let $\varphi : \mathbb{R}^2 \to \mathbb{R}^3$ be a Chevyshev net for a pseudosphere with K = -1. Let ϕ denote the asymptotic angle. Then

 $I = du^{2} + 2\cos\phi \, du \, dv + dv^{2}$ $II = 2\sin\phi \, du \, dv$

Remark that the singular locus of φ is defined by

 Σ : sin $\phi = 0$, i.e., $\phi = k\pi$, $k \in \mathbb{Z}$.

For 2-soliton surface, we have $k = 0, \pm 1$.

Criteria of singularities

Let C denote the curvature line through P whose principal direction is null direction at P.

- 1. Assume that ϕ is nonsingular at P, i.e., the singular locus of ϕ is nonsingular at P.
 - 1.1 φ is cuspidal edge at P if and only if Σ and C intersect transversely at P.
 - 1.2 φ is swallow tail at P if and only if Σ has 2-point contact with C at P.

2. Assume that ϕ has a Morse singularity at P.

- 2.1 φ is cuspidal Beaks at P if and only if the Hessian of ϕ is positive.
- 2.2 φ is cuspidal lips at P if and only if the Hessian of ϕ is negative.

Flecnodal and ridge on a 2-soliton surface

On pseudospheres, we have ∂_u -flecnodal line ($\phi_u = 0$), ∂_v -flecnodal line ($\phi_v = 0$), ∂_x -ridge line ($\phi_x = 0$), ∂_y -ridge line ($\phi_y = 0$) and, on 2-soliton surfaces, they are

 $\frac{\cosh \xi_2}{\cosh \xi_1} = \frac{\lambda_2}{\lambda_1}, \ \frac{\lambda_1}{\lambda_2}, \ \frac{\lambda_2 + \lambda_2^{-1}}{\lambda_1 + \lambda_1^{-1}}, \ \frac{\lambda_2 - \lambda_2^{-1}}{\lambda_1 - \lambda_1^{-1}}, \ \text{respectively}.$

Here $\xi_i = \lambda_i u + v / \lambda_i$, i = 1, 2.

When $\lambda_2 \rightarrow \lambda_1 = \lambda$,

$$\phi_{\lambda,\lambda} = \lim_{\lambda' \to \lambda} \phi_{\lambda,\lambda'} = 4 \tan^{-1} \frac{-\eta}{\cosh \xi},$$

where $\xi = \lambda u + \lambda^{-1}v + c$ and $\eta = \lambda u - \lambda^{-1}v$. The ∂_u -fleenodal, ∂_v -fleenodal, ∂_x -ridge and ∂_y -ridge are defined by

 $\eta \tanh \xi = 1, -1, \ rac{\lambda - \lambda^{-1}}{\lambda + \lambda^{-1}}, \ rac{\lambda + \lambda^{-1}}{\lambda - \lambda^{-1}}, \ extbf{respectively}.$

Classification of 2-soliton

The result in this section should compare the classification of 2-soliton surfaces (Popov). They show four types for generic 2-soliton surfaces. The correspondence between their classification and our results is summarized as follows:

Type	$\lambda_1 \lambda_2$	μ	flecnodal	∂_x -ridge	∂_y -ridge
	+	+	exist	exist	exist
2	+		exist	exist	not exist
3		+	not exists	not exist	not exist
4			not exists	not exist	exist

 $\mu = (\lambda_1^2 - 1)(\lambda_2^2 - 1).$

Breather surfaces

For $\lambda \in \mathbb{C}$, with $\operatorname{Re} \lambda \neq 0$, $\operatorname{Im} \lambda \neq 0$, we have

$$\phi_{\lambda,\bar{\lambda}} = -4 \tan^{-1} \left(\cot \arg \lambda \cdot \frac{\sin \operatorname{Im} \xi}{\cosh \operatorname{Re} \xi} \right)$$

where $\xi = \lambda u + v/\lambda$. The ∂_u -fleenodal, ∂_v -fleenodal, ∂_x -ridge and ∂_y -ridge are defined by

 $\frac{(\tanh \operatorname{Re} \xi)(\tan \operatorname{Im} \xi)}{\tan \operatorname{arg} \lambda} = 1, -1, \frac{|\lambda| - |\lambda|^{-1}}{|\lambda| + |\lambda|^{-1}}, \frac{|\lambda| + |\lambda|^{-1}}{|\lambda| - |\lambda|^{-1}},$ respectively.